

Contents

Acknowledgements	iii
List of Figures	viii
List of Tables	xiii
List of Symbols	xiv

1 Introduction	1
1.1 Problem Statement	1
1.2 Definition of power system stability	2
1.3 Power system oscillations	4
1.3.1 Low frequency oscillations (LFOs)	4
1.3.2 Subsynchronous oscillations (SSOs)	5
1.4 Requirements of a reliable power system	5
1.5 A Brief Review of power system stabilization techniques	7
1.5.1 Conventional stabilizers	8
1.5.2 Adaptive stabilizers	8
1.5.3 Robust stabilizers	9
1.5.4 Fuzzy and adaptive fuzzy stabilizers	9
1.5.5 Necessity for applying decentralized PSSs	10
1.6 Historical background of linear matrix inequalities (LMIs)	11
1.7 Motivation	14
1.8 Thesis objectives	15
1.9 Thesis outline	16

2	The Proposed Design Models of Power Systems	18
2.1	Introduction	18
2.2	Model uncertainty	19
2.2.1	LTI systems	20
2.2.2	Polytopic systems	21
2.2.3	Affine parameter dependent systems	21
2.3	Single-machine infinite-bus system	22
2.3.1	Affine parameter model	25
2.3.2	The 32-vertex system polytopic model (Model A)	27
2.3.2	The 8-vertex system polytopic model (Model B)	27
2.3.4	The 4-vertex system polytopic model (Model C)	28
2.4	Modeling of multimachine power systems	29
2.4.1	Differential algebraic model	30
2.4.2	The linearized model of a multimachine power system	33
2.4.3	Polytopic model of a multimachine power system	36
2.5	Multimachine case study	37
2.5.1	Test power system	37
2.5.2	Kundur's PSS and IEEE-PSS4B	38
2.6	Conclusion	40
3	Robust Syntheses of PSSs: an LMI Approach	42
3.1	Introduction	42
3.2	Augmented model of a SMIB system	44
3.3	Synthesis of robust reduced order output feedback controllers	47
3.3.1	Static output feedback (SOF) stabilization	48

3.3.2	Design of P, PI, PD and PID controllers via SOF	54
3.3.3	Design of reduced order dynamic output feedback controllers	55
3.4	Robust synthesis of multiobjective state feedback controllers	56
3.5	Robust synthesis of multiobjective full order dynamic output feedback controllers	61
3.6	Robust synthesis of decentralized controllers	69
3.7	Simulation results	71
3.7.1	Design validation based on SMIB system	72
3.7.2	Design validation based on a multimachine power system	86
3.8	Conclusion	96
4	Fuzzy Static and Fuzzy Observer-based Output Feedback PSSs	98
4.1	Introduction	98
4.2	Review of Takagi-Sugeno (T-S) fuzzy model and parallel distributed compensation (PDC)	100
4.3	Development of T-S fuzzy design model	103
4.3.1	The 8-rule T-S fuzzy model	103
4.3.2	The 4-rule T-S fuzzy model	105
4.4	Synthesis of a fuzzy static output feedback PSS	107
4.4.1	Synthesis of fuzzy static output feedback PSS via equality constraint	107
4.4.2	Synthesis of fuzzy static output feedback PSS using an ILMI approach	110
4.5	Synthesis of a fuzzy observer-based output feedback PSS	112
4.5.1	Synthesis of fuzzy pole-placement observer-based output feedback PSS	113

4.5.2	Synthesis of suboptimal multiobjective fuzzy observer-based output feedback PSS	115
4.6	Simulation results	117
4.6.1	Simulation results of a SMIB test system	117
4.6.2	Simulation results of multimachine test power system	137
4.7	Conclusion	149
5	Multiobjective Fuzzy State Feedback and Fuzzy Output Feedback PSSs	151
5.1	Introduction	151
5.2	The 32-rule T-S fuzzy model	152
5.3	Synthesis of multiobjective fuzzy state feedback PSS	154
5.4	Synthesis of multiobjective fuzzy dynamic output feedback PSS	158
5.5	Simulation results	164
5.5.1	Simulation results based on SMIB power system	164
5.5.2	Simulation results of the multimachine power system	178
5.6	Conclusion	186
6	Conclusion	188
6.1	Suggestion for future work	194
	Appendix A	196
	Appendix B	222
	Appendix C	223
	References	224
	Publications	234