

Abstract

This thesis presents two design issues to improve the performance of a PSS. The first issue considers the synthesis of a robust PSS while the second issue considers the synthesis of a model-based fuzzy PSS. The design issues are addressed using a linear matrix inequalities (LMIs) approach. Polytopes and Takagi-Sugeno (T-S) fuzzy models can capture major uncertainties in power systems. Three T-S fuzzy models are proposed to represent the uncertainties that occur due to continuous variations in operating conditions.

Robust synthesis of a PSS is addressed considering different controller forms such as state feedback, full-order output feedback, reduced order output feedback and PID controllers. Synthesizing a controller is firstly reduced to an LMI and/or BMI optimization problem. LMI optimization problems are efficiently-solved using available interior point algorithms while for BMIs which are not convex optimization problems, a set of iterative linear matrix inequalities (ILMI) algorithms are developed to find a set of suboptimal controllers. Syntheses of a multiobjective state and output feedback PSSs that guarantee robust pole-clustering and robust performance in terms of H_2 and H_∞ are presented. The structure of a PSS in industry is preserved by considering the design of reduced order output feedback PSSs. Synthesizing robust phase compensators is reduced to solving a set of BMI constraints. After selecting the pole location of a phase compensator-based PSS, the synthesis problem is reduced to a generalized static output feedback (SOF) control problem. Two ILMI algorithms are proposed to solve robust SOF control problems. Further, synthesizing robust PID-based PSS is addressed and reduced to solving SOF control problem using the proposed ILMI algorithms. Synthesizing robust decentralized state feedback, full-order output feedback, reduced order output feedback and PID-based PSSs in multimachine power systems is considered.

The second issue considers the design of model-based fuzzy PSS that guarantees robust stability and robust performance of power systems. This issue is initiated by formulating single-machine power systems as Takagi-Sugeno (T-S) fuzzy models. This issue includes the syntheses of model-based fuzzy state feedback and dynamic output feedback controllers that guarantee a mix of control objectives. Moreover, this issue considers the design of multiobjective fuzzy observer-based output feedback stabilizer that guarantees robust pole-placement in LMI regions and robust performance in terms of H_2 and H_∞ . Sufficient LMI conditions for synthesizing multiobjective fuzzy state feedback and fuzzy dynamic output feedback are presented and proved. Further, sufficient LMI conditions to synthesize a pole-clustering fuzzy observer-based PSS are presented and proved. Sufficient BMIs conditions to synthesize a multiobjective fuzzy observer-based PSS are also proved and an ILMI algorithm is proposed to solve this set of BMIs constraints. The design of fuzzy static output feedback PSS that guarantees robust pole-clustering is considered where the synthesis is reduced to solving a set of LMI constraints together with an equality constraint. Furthermore, the design of fuzzy static output feedback that guarantees certain decay rate and certain H_∞ performance is reduced to solving a set of BMI constraints. Two ILMI algorithms are proposed to find a suboptimal fuzzy static output feedback PSS.

Simulation results of a single-machine and multimachine power system confirm the effectiveness of the proposed designs. In single-machine simulations, the proposed designs are compared to the CPSS while in multimachine simulation the proposed designs are compared to CPSS and to the standard IEEE-PSS4B stabilizer.

Acknowledgments

This thesis was made possible with the help of many people who have inspired me during the last three years I have spent as a graduate student at Benha University. Firstly, I would like to express my deepest gratitude and respect to Prof. Dr. Wagdy Mansour who treated me as a father and as a supervisor. Certainly, Dr. Wagdy is a great person who will affect my life in the future.

I need to thank Prof. Dr. Fahmy Bendary for his great effort to begin and to complete this work in this from. Frankly, I admit that his encouragement and his advices are the major causes that helped me to finish this work. I need to confess that patience of Dr. Fahmy has learned me a lot and will improve my performance in the future.

Finally, I would like to express my deepest gratitude and respect to my academic and research advisor Prof. Dr. Abdel-Latif Elshafei for his guidance and constant support in helping me to conduct and complete this work. His firm grasps and forte on all diverse areas of control and power systems ensured a steady stream of ideas that spawns gateways for solving the problems at hand. He has been a great source of inspiration and I am his student forever.